

**CLAIMS**

We claim:

1           1.     A variable speed wind turbine system comprising:  
2               a wound rotor induction generator;  
3               a torque controller coupled to the generator to control  
4 generator torque using field oriented control; and  
5               a pitch controller coupled to the generator to perform pitch  
6 regulation based on generator rotor speed and operating  
7 independently of the torque controller.

1           2.     The system defined in Claim 1 wherein the pitch  
2 controller comprises a proportional, integral derivative (PID)  
3 pitch controller.

1           3.     The system defined in Claim 1 wherein the pitch  
2 controller comprises a proportional, integral (PI) pitch controller.

1           4.     The system defined in Claim 1 wherein the pitch  
2 controller comprises a proportional, derivative (PD) pitch  
3 controller.

1           5.     The system defined in Claim 1 wherein the pitch  
2 controller comprises a Lag-Lead controller.

1           6.     The system defined in Claim 1 wherein the pitch  
2 controller comprises a Lead-Lag controller.

1           7.     The system defined in Claim 1 where the pitch  
2 controller comprises an open loop controller with a derivative  
3 term.

1           8.     The system defined in Claim 1 wherein the wound  
2 rotor induction generator comprises a non-slip ring induction  
3 generator.

1           9.     The system defined in Claim 1 wherein the torque  
2 controller comprises a dampening filter to reduce commanded  
3 torque based on detected oscillation motion between turbine  
4 blades and the generator.

1           10.    A variable speed system comprising:  
2           a wound rotor induction generation means for generating  
3 power;

4           a torque controlling means for controlling generator torque  
5    using field oriented control; and  
6           a pitch controlling means for performing pitch regulation  
7    based on generator rotor speed and operating independently of  
8    the torque controller.

1           11.    The system defined in Claim 10 wherein the pitch  
2    controlling means comprises a proportional, integral derivative  
3    (PID) pitch controller.

1           12.    A variable speed wind turbine system comprising:  
2           a wound rotor induction generator;  
3           a torque controller coupled to the generator to control  
4    generator torque using field oriented control; and  
5           a proportional, integral derivative (PID) pitch controller  
6    coupled to the generator to perform pitch regulation based on  
7    generator rotor speed.

1           13.    The system defined in Claim 12 wherein the wound  
2    rotor induction generator comprises a non-slip ring induction  
3    generator.

1           14.    The system defined in Claim 12 wherein the power  
2   controller controls the generator power and torque as a function  
3   of generator speed.

1           15.    The system defined in Claim 12 wherein the power  
2   controller controls the generator power from a power look up  
3   table (LUT) as a function of generator speed using field oriented  
4   control (FOC).

1           16.    The system defined in Claim 12 wherein the power  
2   controller comprises a look up table (LUT) of power and  
3   corresponding generator rotor speeds, and wherein the power  
4   controller interpolates the LUT using a measured generator rotor  
5   speed to determine a target output power, from which the torque  
6   controller determines a desired generator torque using the  
7   measured generator rotor speed. ,

1           17.    The system defined in Claim 16 wherein the power  
2   controller causes the generator to follow a predetermined power-  
3   speed curve encoded in the LUT.

1           18.    The system defined in Claim 12 wherein the power  
2   controller comprises:

3           a LUT encoding a predetermined power-speed curve,  
4   wherein the LUT outputs a target output power in response to a  
5   measured generator rotor speed;  
6           a comparator to generate a power error indication based on  
7   a comparison of actual output power to the target output power;  
8           a proportional, integral (PI) controller coupled to the power  
9   error indication to generate an adjusted actual output power in  
10   response to the calculated power error indication; and  
11           a divider to generate a commanded torque in response to  
12   the measured generator rotor speed and the adjusted actual  
13   output power.

1           19.   The system defined in Claim 18 further comprising a  
2   feedforward dampening term filter coupled to change the  
3   commanded torque in response to the measured generator rotor  
4   speed.

1           20.   The system defined in Claim 12 wherein the power  
2   controller controls generator torque by commanding a required  
3   rotor current vector which interacts with an identified flux vector  
4   to produce a desired generator torque.

1           21.    The system defined in Claim 12 wherein the power  
2 controller controls torque at least from cut-in to rated wind  
3 speeds.

1           22.    The system defined in Claim 12 wherein the power  
2 controller controls torque from cut-in to rated wind speeds.

1           23.    The system defined in Claim 12 wherein the power  
2 controller causes the generator to follow a predetermined power-  
3 speed curve.

1           24.    The system defined in Claim 12 wherein the power  
2 controller commands a preselected constant torque to slow the  
3 wound rotor.

1           25.    The system defined in Claim 24 wherein the  
2 preselected constant torque comprises a maximum preselected  
3 constant torque.

1           26.    The system defined in Claim 12 further comprising a  
2 generator speed indication coupled to inputs of the power  
3 controller and the PID controller.

1           27.    The system defined in Claim 12 wherein the power  
2 controller operates independently of the PID pitch controller.

1           28.    The system defined in Claim 12 wherein the PID  
2 pitch controller comprises a closed loop PID controller with pitch  
3 angle being fed back.

1           29.    The system defined in Claim 12 wherein the PID  
2 pitch controller comprises an open loop controller with a  
3 derivative term.

1           30.    The system defined in Claim 12 wherein the PID  
2 pitch controller generates a pitch velocity to perform pitch  
3 regulation.

1           31.    The system defined in Claim 12 further comprises a  
2 wind turbine having at least one blade coupled to the generator,  
3 and wherein the PID pitch controller controls generator rotor  
4 speed by pitching said at least one blade.

1           32.    The system defined in Claim 31 wherein the PID  
2 pitch controller pitches said at least one blade based on a

3 difference in actual generator rotor speed and commanded  
4 generator rotor speed.

1        33.    The system defined in Claim 12 further comprising:  
2        a comparator to generate speed error indication based on a  
3 comparison between a measured generator rotor speed and a  
4 target generator rotor speed, and wherein the PID pitch controller  
5 generates an output pitch velocity value in response to the speed  
6 error indication; and  
7        a non-linear LUT coupled to output a command voltage to  
8 drive a proportional valve to effect pitching action in response to  
9 the pitch velocity value.

1        34.    A variable speed wind turbine having a plurality of  
2 blades comprising:  
3        a doubly-fed generator having a wound rotor;  
4        a power converter coupled to the wound rotor of the  
5 doubly-fed generator and having a LUT containing an encoded  
6 power-speed curve, wherein the power converter samples  
7 generator rotor speed, updates a desired output power from the  
8 LUT using the generator rotor speed, determines a new torque  
9 based on an updated desired output power, and calculates a new  
10 current vector that is impressed upon the wound rotor; and



11           a closed loop proportional, integral derivative (PID) pitch  
12 controller coupled to pitch the plurality of blades based on  
13 generator rotor speed.

1           35.   The turbine defined in Claim 34 wherein the power  
2 converter and PID pitch controller operate independently.

1           36.   The turbine defined in Claim 34 wherein the power  
2 converter holds power constant above rated wind speeds.

1           37.   The turbine defined in Claim 36 wherein the power  
2 converter holds power constant by controlling rotor current to  
3 provide the proper torque.

1           38.   The turbine defined in Claim 34 wherein the PID  
2 pitch controller generates a pitch velocity to perform pitch  
3 regulation.

1           39.   The turbine defined in Claim 34 wherein the PID  
2 pitch controller pitches the plurality of blades based on a  
3 difference in actual generator rotor speed and commanded  
4 generator rotor speed.

1           40.    The turbine defined in Claim 34 further comprising:  
2                a comparator to generate a speed error indication based on a  
3 comparison between a measure generator rotor speed and a target  
4 generator rotor speed, and wherein the PID pitch controller  
5 generates a pitch velocity command in response to the speed error  
6 indication; and  
7                a non-linear LUT coupled to output a drive voltage to be  
8 applied to a proportional value to accomplish blade pitch motion  
9 in response to the pitch velocity command.

1           41.    A variable speed wind turbine having a plurality of  
2 blades comprising:  
3                a doubly-fed generation means for generating power,  
4 wherein the generation means has a wound rotor;  
5                a power converting means for transforming alternating  
6 current to direct current, wherein, the power converting means  
7 has a LUT containing an encoded power-speed curve, wherein the  
8 power converting means includes means for sampling generator  
9 rotor speed, means for updating a desired output power from the  
10 LUT using the generator rotor speed, means for determining a  
11 new torque based on an updated desired output power, and  
12 means for calculating a new current vector that is impressed upon  
13 the wound rotor; and

14           a closed loop proportional, integral derivative (PID) pitch  
15   controlling means for pitching the plurality of blades based on  
16   generator rotor speed.

1           42.   The turbine defined in Claim 41 wherein the power  
2   converting means and PID pitch controlling means operate  
3   independently.

1           43.   The turbine defined in Claim 41 wherein the power  
2   converting means includes means for holding power constant  
3   above rated wind speeds.

1           44.   The turbine defined in Claim 43 wherein the power  
2   converting means includes means for holding power constant by  
3   controlling rotor current to provide the proper torque.  
4

1           45.   A method of controlling generator power  
2   comprising the steps of:  
3       measuring generator rotor speed;  
4       accessing a LUT using measured rotor speed to obtain a  
5   target output power;

6        comparing actual output power and the target output  
7 power;

8        generating a commanded torque by adjusting a torque  
9 calculation to maintain a predetermined output based on  
10 comparison of actual output power to the target output power.

1        46.    The method defined in Claim 45 wherein the  
2 commanded torque comprises a predetermined constant torque to  
3 slow down the generator rotor speed.

1        47.    The method defined in Claim 45 wherein the  
2 predetermined constant torque comprises a maximum constant  
3 torque.

1        48.    An apparatus for controlling generator power  
2 comprising the steps of:  
3        means for measuring generator rotor speed;  
4        means for accessing a LUT using measured rotor speed to  
5 obtain a target output power;  
6        means for comparing actual output power and the target  
7 output power;

8 means for generating a commanded torque by adjusting a  
9 torque calculation to maintain a predetermined output based on  
10 comparison of actual output power to the target output power.

1 49. A method of controlling generator torque of a  
2 variable speed system, said method comprising the steps of:  
3 identifying a stator flux vector;  
4 commanding a rotor current vector; and  
5 producing a desired generator torque by interacting the  
6 stator flux vector and the rotor current vector.

1 50. A synchronization process for a variable speed  
2 system having a generator, said process comprising the steps of:  
3 connecting a generator stator;  
4 connecting a generator rotor;  
5 ramping up a rotor current; and  
6 regulating generator torque.

1 51. The process defined in Claim 50 wherein the step of  
2 connecting the generator stator occurs at a first generator speed.

1 52. The process defined in Claim 51 wherein the step of  
2 connecting the generator rotor occurs at a second generator speed

3 higher than the first generator speed and when rotor voltage is at  
4 a first voltage.

1 53. The process defined in Claim 52 wherein the step; of  
2 regulating generator torque comprises the steps of enabling a rotor  
3 side converter and gating rotor side IGBTs.

1 54. The process defined in Claim 52 wherein the step of  
2 regulating generator torque comprising the step of creating a  
3 current vector that is able to produce the desired torque.

1 55. A variable speed wind turbine system having  
2 turbine blades, the system comprising:  
3 a wound rotor induction generator;  
4 a torque controller coupled to the generator to control  
5 generator torque, wherein the torque controller comprises a  
6 dampening filter to reduce commanded torque based on detected  
7 oscillation motion between the turbine blades and the generator;  
8 and  
9 a pitch controller coupled to the generator to perform pitch  
10 regulation based on generator rotor speed and operating  
11 independently of the torque controller.

- 1           56.    The system defined in Claim 55 wherein the
- 2   dampening filter comprises a bandpass filter with a passband
- 3   centered at the resonant frequency of the generator and turbine
- 4   blades and a shaft coupling the generator and turbine blades
- 5   together.